


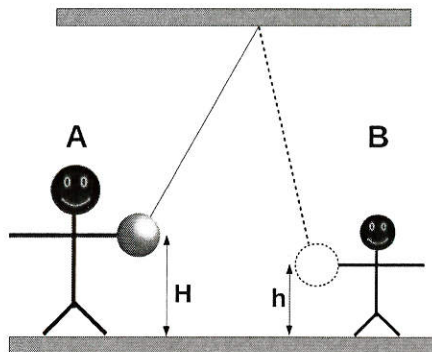
Physics 3210, Spring 2018
Exam #2

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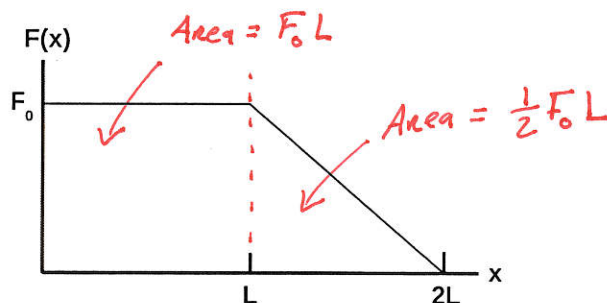
Please read the following before continuing:

- Show all work in answering the following questions. Partial credit may be given for problems involving calculations.
- Be sure that your final answer is clearly indicated, for example by drawing a box around it.
- Be sure that your cellphone is turned off.
- Your signature above indicates that you have neither given nor received unauthorized assistance on any part of this exam.
- Thanks, and good luck!

1. (8 pts) Alice (A) is holding a pendulum bob of mass m at a height H above the ground (solid line). At time $t = t_0$, she releases the bob from rest, and it swings until caught and brought to rest by Brad (B) at a lesser height h at time $t = t_1$ (dashed line). The following questions pertain to the work done on the bob between t_0 and t_1 only. Be sure to give both magnitudes and signs in your answers.



- (a) (2) What work did Alice do on the bob? \emptyset
- (b) (2) What work did gravity do on the bob? $mg(H-h)$
- (c) (2) What work did tension do on the bob? \emptyset
- (d) (2) What work did Brad do on the bob? $-mg(H-h)$
2. (8 pts) The graph below shows the force applied in the positive x -direction, to an object of mass m as a function of position x . The object starts at rest. The force is constant F_0 until the object reaches $x = L$, then it decreases linearly to zero until the object reaches $x = 2L$. What is the speed of the object at $x = 2L$?



Work-Energy Theorem: $Work = \Delta K.E.$

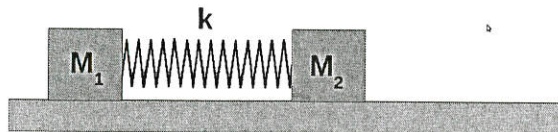
$$Work\ Done = \int F \cdot dx = F_0 L + \frac{1}{2} F_0 L = \frac{3}{2} F_0 L$$

$$\Delta KE = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2 \rightarrow = 0, \text{ STARTS AT REST}$$

$$\frac{3}{2} F_0 L = \frac{1}{2} m v_f^2$$

$$v_f = \sqrt{\frac{3 F_0 L}{m}}$$

3. (14 pts) Two blocks with mass M_1 and M_2 are connected by a spring with spring constant k and are sliding on a frictionless horizontal surface. Their positions are given by coordinates x_1 and x_2 respectively, defined such that when $x_1 = x_2$ the spring is unstretched.



- (a) (4) Write down the Lagrangian for this system.

$$\mathcal{L} = K - U = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2 - \frac{1}{2} k (x_1 - x_2)^2$$

- (b) (4) Use the Lagrangian to determine two coupled equations of motion for the two blocks.

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}_1} - \frac{\partial \mathcal{L}}{\partial x_1} = m_1 \ddot{x}_1 + k(x_1 - x_2) = 0$$

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}_2} - \frac{\partial \mathcal{L}}{\partial x_2} = m_2 \ddot{x}_2 - k(x_1 - x_2) = 0$$

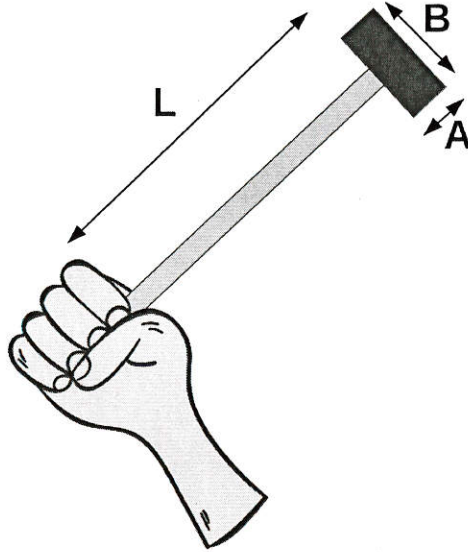
- (c) (6) Show that if M_1 is moving with constant velocity then M_2 must also be moving with constant velocity.

ADD THE TWO EQUATIONS: $m_1 \ddot{x}_1 + m_2 \ddot{x}_2 = 0$

$$\ddot{x}_2 = -\frac{m_1}{m_2} \ddot{x}_1$$

IF $\ddot{x}_1 = 0$ (m_1 CONSTANT VELOCITY) THEN $\ddot{x}_2 = 0$ QED

4. (6 pts) A carpenter swings a hammer to strike a nail. The hammer consists of a handle (thin rod) of mass m and length L , and a rectangular head of width A , length B and mass M . Calculate the moment of inertia of the hammer, about the end of the hammer in the carpenter's hand.



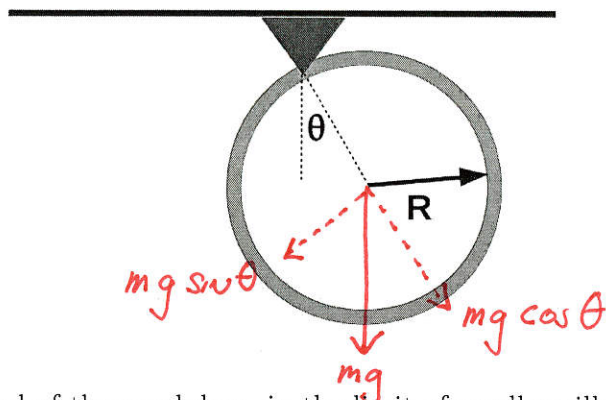
$$I_{\text{HAMMER}} = I_{\text{ROD}} + I_{\text{HEAD}}$$

$$I_{\text{ROD}} = \frac{1}{3} m L^2 \quad (\text{TABLE})$$

$$I_{\text{HEAD}} = I_{\text{cm}} + M R_{\text{cm}}^2 \quad (\text{Parallel Axis Theorem})$$
$$= \frac{1}{12} M (A^2 + B^2) + M (L + \frac{1}{2})^2$$

$$I_{\text{HAMMER}} = \frac{1}{3} m L^2 + \frac{1}{12} M (A^2 + B^2) + M (L + \frac{1}{2})^2$$

5. (16 pts) A pendulum consists of a thin ring of mass M and radius R , attached to a pivot at a point on its rim.



- (a) (8) Compute the period of the pendulum, in the limit of small oscillations.

$$I_{RWA} = I_{ring, CM} + MR_{cm}^2 \text{ (Parallel Axis Theorem)} = MR^2 + MR^2 = \underline{\underline{2MR^2}}$$

$$\sum \tau = MgR \sin \theta = I_{\alpha} = -2MR^2 \ddot{\theta}$$

$$\ddot{\theta} + \frac{1}{2} \frac{g}{R} \sin \theta = 0$$

$$\ddot{\theta} + \frac{1}{2} \frac{g}{R} \theta = 0$$

Small Oscillations

This is SHO Equation with $\omega = \sqrt{\frac{g}{2R}}$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{2R}{g}}$$

Problem continued on the following page.

- (b) (8) Write a particular solution for the pendulum's motion in the case that it is initially hanging vertically and has initial angular velocity ω_0 clockwise.

General solution $\theta(t) = A \cos(\omega t + \phi)$

$$\dot{\theta}(t) = -\omega A \sin(\omega t + \phi)$$

Initial conditions

$$\theta(0) = A \cos \phi = 0 \rightarrow \phi = \pi/2$$

$$\dot{\theta}(0) = -\omega A \sin(\pi/2) = -\omega A = -\omega_0$$

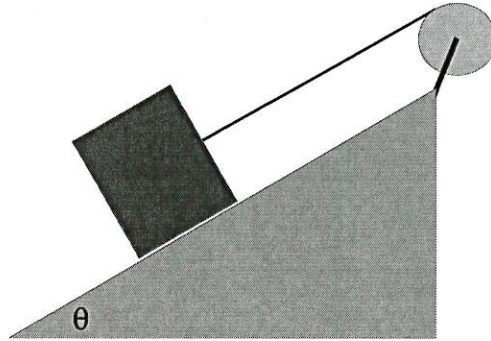
↑
clockwise

$$A = \frac{\omega_0}{\omega} = \omega_0 \sqrt{\frac{2R}{g}}$$

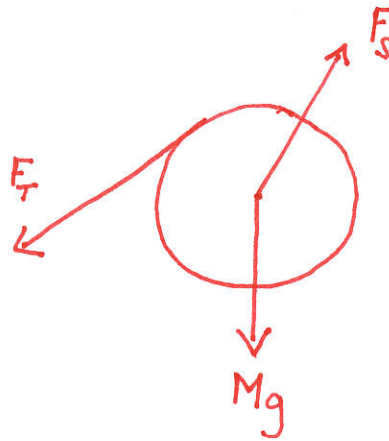
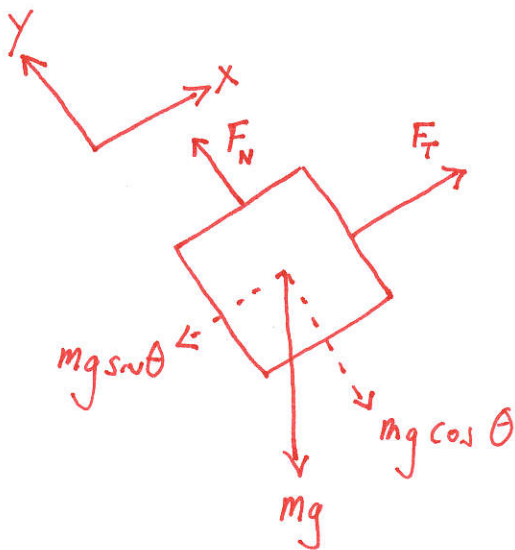
Finally,

$$\theta(t) = \omega_0 \sqrt{\frac{2R}{g}} \cos\left(\sqrt{\frac{2R}{g}} t + \frac{\pi}{2}\right)$$

6. (16 pts) A block of mass m is held by a long massless string on a frictionless inclined plane inclined at an angle θ to the horizontal. The string is wound on a uniform solid cylindrical drum of mass M and radius R as shown in the figure. The drum is given an initial angular speed ω such that the block starts moving up the plane.



- (a) (8) Draw complete *Free Body Diagrams* for the block and drum. Be sure to indicate *all* forces acting on each.



Problem continued on the following page.

(b) (8) Find the tension in the string during the motion.

on block $\sum F_x = F_T - mg \sin \theta = ma_x$

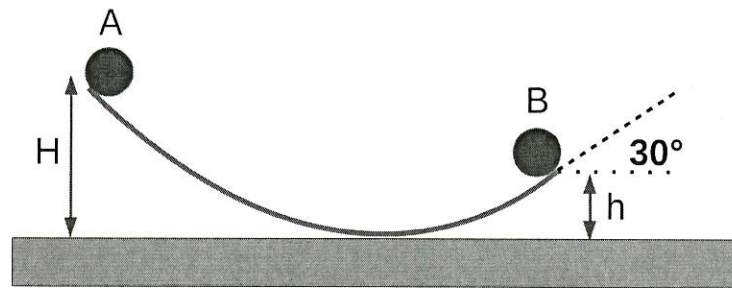
on Drum $\sum \tau = F_T R = I \alpha = -\left(\frac{1}{2}MR^2\right)\frac{a_x}{R}$

$$a_x = -\frac{2F_T}{M}$$

plug into block Eqn $F_T = mg \sin \theta + ma_x$
 $= mg \sin \theta - m \cdot \frac{2F_T}{M}$

$$F_T = \frac{mg \sin \theta}{\left(1 + \frac{2m}{M}\right)}$$

7. (16 pts) A solid disk of radius R and mass m is released from rest at Point A on a curved ramp, at a height H above the bottom. The disk rolls without slipping to B, at which point it leaves the ramp at an angle of 30° with respect to horizontal.



- (a) (10) In terms of m , g , R , H and h , what is the *angular* speed of the disk at point B?

$$mgH = mgh + \frac{1}{2}mv_B^2 + \frac{1}{2}I\omega_B^2$$

$$I = \frac{1}{2}mR^2 \text{ (disk)} \quad \omega = v/R \quad \text{(roll without slipping)}$$

$$mgH = mgh + \frac{1}{2}mv_B^2 + \frac{1}{4}mv_B^2$$

$$gH = gh + \frac{3}{4}v_B^2$$

$$v_B = \sqrt{\frac{4g(H-h)}{3}} \rightarrow \boxed{\omega_B = \frac{v_B}{R} = \sqrt{\frac{4g(H-h)}{3R^2}}}$$

Problem continued on the following page.

- (b) (6) What is the horizontal distance the disk will travel before reaching its maximum height?

$$V_y = V_{oy} + at = V_{oy} - gt$$

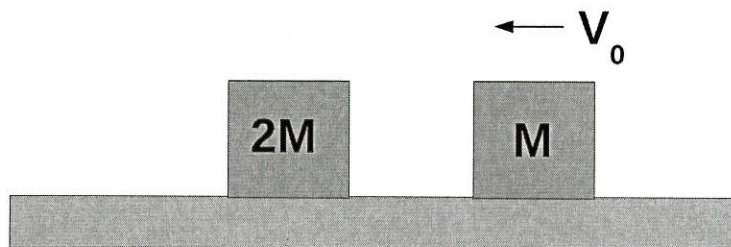
At maximum height, $V_y = 0$, $t = \frac{V_{oy}}{g} = \frac{V_B \sin 30^\circ}{g} = \frac{V_B}{2g}$

$$X - X_0 = V_{ox} t = V_B \cos 30^\circ \cdot \frac{V_B}{2g}$$

$$= \sqrt{\frac{3}{4}} \frac{V_B^2}{2g} = \sqrt{\frac{3}{4}} \cdot \frac{4g(H-h)}{3} \cdot \frac{1}{2g}$$

$$\boxed{X - X_0 = \sqrt{\frac{1}{3}} (H-h)}$$

8. (16 pts) Two blocks, as shown in the figure, are on a frictionless surface. A block with mass M slides to the left with speed v_0 , until it collides elastically with a block of mass $2M$ which is initially at rest. Calculate the final velocities (magnitude and direction) of the two blocks, \vec{v}_1 and \vec{v}_2 .



Conserve Energy (ELASTIC)

$$\frac{1}{2} m v_0^2 = \frac{1}{2} m v_1^2 + \frac{1}{2} (2m) v_2^2$$

$$v_0^2 = v_1^2 + 2v_2^2$$

$$v_1 = \sqrt{v_0^2 - 2v_2^2}$$

Conserve Momentum (No extl Forces)

$$m v_0 = m v_1 + 2m v_2$$

$$v_0 = v_1 + 2v_2$$

$$v_0 = \sqrt{v_0^2 - 2v_2^2} + 2v_2$$

Now some arithmetic...

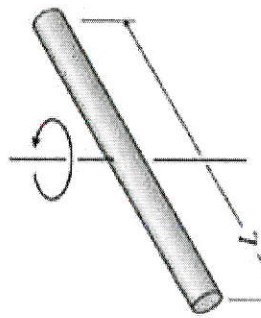
$$(v_0 - 2v_2)^2 = v_0^2 - 2v_2^2$$

$$\cancel{v_0^2} + 4v_2^2 - 4v_0v_2 = \cancel{v_0^2} - 2v_2^2$$

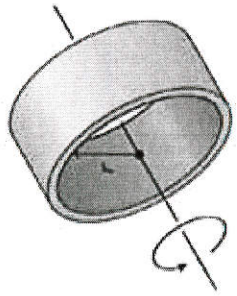
$$\boxed{\vec{v}_2 = +\frac{2}{3} v_0 ; \text{ TO LEFT}}$$

$$v_1 = v_0 - 2v_2 = v_0 - \frac{4}{3} v_0 = -\frac{1}{3} v_0$$

$$\boxed{\vec{v}_1 = \frac{1}{3} v_0 ; \text{ TO RIGHT}}$$

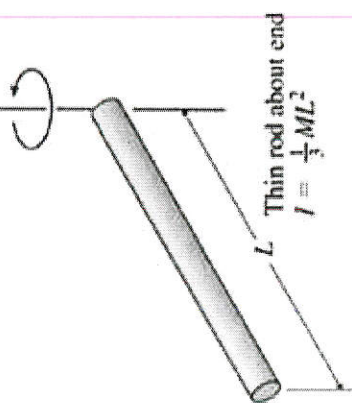
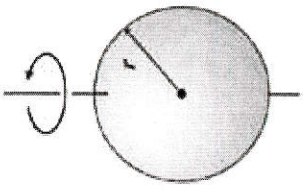


Thin rod about center
 $I = \frac{1}{12} ML^2$

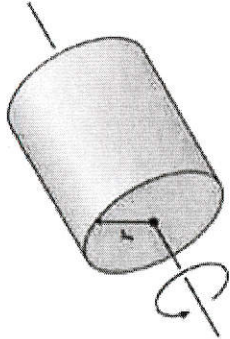


Thin ring or hollow cylinder
 about its axis
 $I = MR^2$

Solid sphere about diameter
 $I = \frac{2}{5} MR^2$

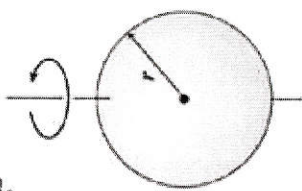


Thin rod about end
 $I = \frac{1}{3} ML^2$

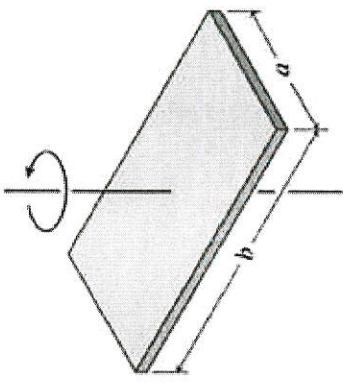


Disk or solid cylinder
 about its axis
 $I = \frac{1}{2} MR^2$

Hollow spherical shell about diameter
 $I = \frac{2}{3} MR^2$



Flat plate about perpendicular axis
 $I = \frac{1}{12} M (a^2 + b^2)$



Flat plate about central axis
 $I = \frac{1}{12} Ma^2$

